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Mammou et al.

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(54) POINT CLOUD GEOMETRY COMPRESSION

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(Continued)

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CPC .. H04N 19/597; H04N 19/182; H04N 19/167; H04N 19/59; H04N 19/119; H04N 19/132; G06T 17/00; G06T 2210/56

See application file for complete search history.

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(57) ABSTRACT

A system comprises an encoder configured to compress a point cloud comprising a plurality of points each point comprising spatial information for the point. The encoder is configured to sub-sample the points and determine subdivision locations for the subsampled points. Also, the encoder is configured to determine, for respective subdivision location, if a point is to be included, not included, or relocated relative to the subdivision location. The encoder encodes spatial information for the sub-sampled points and encodes subdivision location point inclusion/relocation information to generate a compressed point cloud. A decoder recreates an original or near replica of an original point cloud based on the spatial information and the subdivision location inclusion/relocation information included in the compressed point cloud.

20 Claims, 11 Drawing Sheets

